

# Lebesgue Constants and Optimal Node Systems via Symbolic Computations

Short Paper

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## Abstract

Polynomial interpolation is a classical method to approximate continuous functions by polynomials. To measure the correctness of the approximation, Lebesgue constants are introduced. For a given node system  $X^{(n+1)} = \{x_1 < \dots < x_{n+1}\} (x_j \in [a, b])$ , the Lebesgue function  $\lambda_n(x)$  is the sum of the modulus of the Lagrange basis polynomials built on  $X^{(n+1)}$ . The Lebesgue constant  $\Lambda_n$  assigned to the function  $\lambda_n(x)$  is its maximum over  $[a, b]$ . The Lebesgue constant bounds the interpolation error, i.e., the interpolation polynomial is at most  $(1 + \Lambda_n)$  times worse than the best approximation. The minimum of the  $\Lambda_n$ 's for fixed  $n$  and interval  $[a, b]$  is called the optimal Lebesgue constant  $\Lambda_n^*$ . For specific interpolation node systems such as the equidistant system, numerical results for the Lebesgue constants  $\Lambda_n$  and their asymptotic behavior are known [3, 7]. However, to give explicit symbolic expression for the minimal Lebesgue constant  $\Lambda_n^*$  is computationally difficult. In this work, motivated by Rack [5, 6], we are interested for expressing the minimal Lebesgue constants symbolically on  $[-1, 1]$  and we are also looking for the characterization of the those node systems which realize the minimal Lebesgue constants. We exploited the equioscillation property of the Lebesgue function [4] and used quantifier elimination and Groebner Basis as tools [1, 2]. Most of the computation is done in Mathematica [8].

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## References

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